

SLEW RATE CONTROL OF OUTPUT DRIVERS USING FETS WITH  
DIFFERENT THRESHOLD VOLTAGES

Field of the Invention

5        The present invention relates generally to integrated circuit pad circuits, and more particularly to controlling the slew rate of output drivers using transistors with differing threshold voltages.

Background of the Invention

10      Integrated circuits communicate with one another using digital signals. In the digital world, a digital signal may be in one of a plurality of predefined quantized states. Because digital signals are transmitted using an analog signal along a transmission line, the predefined quantized states of the digital signal are represented by different ranges of voltages within the total voltage range of the signal. For example, a typical digital integrated circuit (IC) will communicate using two states - zero and one. The digital state of zero is represented by the range of voltages between a minimum voltage  $V_{MIN}$  (e.g., 0 volts) of the potential voltage range of the signal and a voltage  $V_{LOW}$  that is low relative to the total range of voltage, whereas the digital state of one is represented by the range of voltages between a voltage  $V_{HIGH}$  that is high relative to the total range of voltages and a maximum voltage  $V_{MAX}$  (e.g., 1.5 volts) of the potential voltage range of the signal. In this example, the state of the digital signal is unknown when the voltage level of the signal is between  $V_{LOW}$  and  $V_{HIGH}$ , which typically only occurs during transitions of the signal from either the zero state to the one state or vice versa.

15      Because the transmission signal is actually analog, the transition between digital states does not occur instantaneously, but instead occurs over a period of time  $T_{TRANSITION}$  that is dependent on the physical conditions present on the transmission line. It is well known that signal transitions over a transmission line will suffer a delay known as a propagation delay due to the parasitic resistance, inductance, and capacitance of the line. This delay increases with the length of the line. In addition, it is also well-known that

unless the impedance of the transmission line matches that of the load it drives, the signal will degrade because the mismatch in impedance leads to reflections from the load that are passed back to the driver circuit. The driver circuit then re-reflects the reflection causing further signal degradation.

5        Unfortunately, when the driver circuit drives multiple loads with differing impedances, the transmission line requires multiple stubs to properly match each of the loads during realtime operation. However, the use of multiple stubs then generates multiple reflections. One way of ensuring proper detection of signal states is to control the edge rates of the  
10      signal.

However, this competes with the trend towards ever increasing signal frequencies, which results in higher edge rates. Accordingly, a need exists for a technique for controlling the slew rate of signal edge transitions without sacrificing the signal frequency.

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#### Summary of the Invention

The present invention is a method and circuit for controlling the slew rate of integrated circuit output drivers using transistors with differing threshold voltages to allow a stepped-stage slew rate on the transition edges  
20      of a digital signal.

In accordance with the method of the invention, a number of switchably conductive devices such as FETs each characterized by a different threshold voltage are connected in parallel between a transmission line node such as the output pad and a voltage source. Each conductive  
25      device is controllable at a respective switch using a common driving signal. Accordingly, when the driving signal transitions from one digital state to another, the conductive devices will each turn on or off (depending on the direction of the signal transition) in turn to generate a stepped control of the slew rate of the signal edge on the node.

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Brief Description of the Drawing

The invention will be better understood from a reading of the following detailed description taken in conjunction with the drawing in which like reference designators are used to designate like elements, and in which:

5 FIG. 1A is an operational flowchart of a method for adjusting the amount of current conducted to the output pad in order to slow down the edge rate of the signal on the output pad by incrementally increasing the amount of current conducted to the output pad;

10 FIG. 1B is an operational flowchart of a method for adjusting the amount of current conducted to the output pad by incrementally decreasing the amount of current conducted to the output pad;

FIG. 2 is a schematic diagram of a slew-rate controlled output driver circuit implemented in accordance with the invention;

15 FIG. 3A is a voltage-vs.-timing diagram illustrating a driving voltage signal;

FIG. 3B is a voltage-vs.-timing diagram illustrating the output signal seen on the output pad as a result of the driving voltage signal of FIG. 3A;

FIG. 4 is an alternative embodiment of a slew rate controlled output driver circuit implemented in accordance with the invention;

20 FIG. 5 is an operational flowchart of an exemplary embodiment of a method in accordance with the invention for implementing a circuit for controlling the slew rate of output drivers by using transistors with differing threshold voltages to achieve a stepped-stage slew rate on the edges of the signal transitions; and

25 FIG. 6 is an operational flowchart of a method for operating a circuit built in accordance with FIG. 5.

Detailed Description

A novel method and circuits for controlling the slew rate of output drivers using transistors with differing threshold voltages is described in detail hereinafter. Although the invention is described in terms of specific illustrative embodiments, such as specific output driver designs, it is to be understood that the embodiments described herein are by way of example

only and the scope of the invention is not intended to be limited thereby but is intended to extend to any embodiment incorporating any number of transistors of any type with differing threshold voltages that results in stepped-stage slew rate on the edges of signal transitions.

Turning now in detail to the drawing, FIGS. 1A and 1B illustrate an exemplary embodiment of methods in accordance with the invention for controlling the slew rate of output drivers by using transistors with differing threshold voltages to achieve a stepped-stage slew rate on the edges of the signal transitions. In particular, the invention employs switchably conductive devices such as field effect transistors (FETs) with varying threshold voltages. It is known in the art that FETs may be designed with varying specifications. For example, the FETs most commonly used in integrated circuits due to their lower voltage ratings have a threshold voltage between 0.4-0.5 volts. FETs designed for use in higher power applications typically have a threshold voltage between 0.6 and 0.7 volts. This 200-300 mV difference is used to advantage in the present invention to achieve a stepped-stage slew rate on the signal edges as discussed hereinafter.

FIG. 1A illustrates a method 10 for adjusting the amount of current conducted to the output pad in order to slow down the edge rate of the signal on the output pad by incrementally increasing the amount of current conducted to the output pad. As shown in FIG. 1A, the driving voltage, which controls the amount of current to conduct to the output pad, is sensed 12. When the driving voltage reaches a first threshold, for example voltage corresponding to the lowest threshold voltage of all conductive devices coupled to the output pad, as determined in step 14, the amount of current conducted to the pad is stepped up 16, for example from no current conduction to a first increment of conduction. When the driving voltage reaches a next threshold, for example voltage corresponding to the next highest threshold voltage of all conductive devices coupled to the output pad, as determined in step 18, the amount of current conducted to the pad is stepped up 20 to a higher level. Steps 18 and 20 may be repeated for additional higher threshold voltage levels of additional conductive devices coupled to the output pad.

FIG. 1B illustrates a method 30 for adjusting the amount of current conducted to the output pad in order to slow down the edge rate of the signal on the output pad by incrementally decreasing the amount of current conducted to the output pad. As shown in FIG. 1B, the driving voltage, which controls the amount of current to conduct to the output pad, is sensed 32.

When the driving voltage reaches a first threshold, for example voltage corresponding to the highest threshold voltage of all conductive devices coupled to the output pad, as determined in step 34, the amount of current conducted to the pad is stepped down 36, for example from maximum current conduction to a smaller amount of conduction. When the driving voltage reaches a next threshold, for example voltage corresponding to the next lowest threshold voltage of all conductive devices coupled to the output pad, as determined in step 38, the amount of current conducted to the pad is stepped down 40 to a lower level. Steps 38 and 40 may be repeated for additional lower threshold voltage levels of additional conductive devices coupled to the output pad.

As will become apparent in the description hereinafter, the two methods 10 and 30 may alternatively operate to drive a single data signal.

Turning now to a specific preferred embodiment, FIG. 2 depicts a slew rate controlled output driver circuit 100 in accordance with the present invention. As will be described in detail hereinafter, the slew-rate controlled output driver circuit 100 of FIG. 2 provides the functionality for controlling the slew rate of the signal driven onto the output pad by performing a step-controlled edge transition.

As known in the art, a typical output driver will include at least an inverter 110 having an input coupled to receive a data signal and an output coupled to the gate of a transistor whose drain is coupled to an output pad 150 and whose source is coupled to either a high voltage source (e.g.,  $V_{DD}$ ) for driving the output pad to a high voltage level, or a low voltage source (e.g.,  $V_{SS}$  or ground) for driving the output pad to a low voltage level. In the illustrative embodiment of FIG. 2, the circuitry is implemented using field effect transistors (FETs). Furthermore, the output driver 100 includes two stages: drive high stage S1 and drive low stage S2.

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As shown, drive high stage S1 includes a first inverter 110 which receives data signal DATA. The output of the inverter is connected to the gate of a low-voltage p-channel FET (PFET)  $P_{LV}$  and to the gate of a high-voltage PFET  $P_{HV}$ . The sources of PFETs  $P_{LV}$  and  $P_{HV}$  are each connected to the circuit high-voltage source  $V_{DD}$ , and their drains are each connected to the pad node 150.

Drive low stage S2 includes a second inverter 120 which also receives data signal DATA. The output of the inverter is connected to the gate of a low-voltage n-channel FET (NFET)  $N_{LV}$  and to the gate of a low-voltage NFET  $N_{HV}$ . The sources of NFETs  $N_{LV}$  and  $N_{HV}$  are each connected to the circuit ground, and their drains are each connected to the pad node 150.

Referring now also to FIGS. 3A and 3B in conjunction with FIG. 2, in operation, when the data signal DATA transitions from a low to a high voltage level, inverters 110 and 120 will both output a low voltage level. Accordingly, a low voltage level is applied to the gates of PFETs  $P_{LV}$  and  $P_{HV}$ , turning them both on, in a staged manner, to source a high-voltage level  $VDD$  onto the pad node 150. Because low-voltage PFET  $P_{LV}$  is characterized by a lower threshold voltage than high-voltage PFET  $P_{HV}$ , PFET  $P_{LV}$  will turn on sooner than PFET  $P_{HV}$ , as illustrated at  $P_{LV\_ON}$  and  $P_{HV\_ON}$  in FIG. 3A. Since PFETs  $P_{LV}$  and  $P_{HV}$  operate as resistors coupled in parallel, the voltage level on the output pad, shown in FIG. 3B, transitions more slowly during the period of time when only the low-voltage PFET is on, and more quickly when the high-voltage PFET turns on. Accordingly, the addition of the high-voltage PFET  $P_{HV}$  in parallel with the low-voltage PFET  $P_{LV}$  allows a stepped-stage slew rate of the edge transition, where the slew rate of each stage is controlled by the sizing of the low- and high-voltage PFETs  $P_{LV}$  and  $P_{HV}$ .

Whenever the data signal DATA is high, resulting in a low voltage level output by inverters 110 and 120 and the application of a low voltage level to the gates 112 and 132 of PFETs  $P_{LV}$  and  $P_{HV}$ , a low voltage level is simultaneously applied to the gates 122 and 142 of NFETs  $N_{LV}$  and  $N_{HV}$ . The application of the low voltage levels to the gates 122 and 142 of NFETs

N<sub>LV</sub> and N<sub>HV</sub> turns off NFETs N<sub>LV</sub> and N<sub>HV</sub> to isolate the pad node 150 from ground when the pad is being driven high. Because low-voltage NFET P<sub>LV</sub> is characterized by a lower threshold voltage than high-voltage NFET P<sub>HV</sub>, high-voltage NFET N<sub>HV</sub> will turn off sooner than low-voltage NFET N<sub>LV</sub>, as illustrated at N<sub>LV</sub>\_ON and N<sub>HV</sub>\_ON in FIG. 3A. Just as in the case of the high-voltage PFETs P<sub>LV</sub> and P<sub>HV</sub>, low-voltage NFETs N<sub>LV</sub> and N<sub>HV</sub> operate together as resistors coupled in parallel. Accordingly, the voltage level on the output pad 150 (shown in FIG. 3B) transitions more quickly during the period of time when both the high- and low-voltage NFETs N<sub>HV</sub> and N<sub>LV</sub> are on and more slowly when only the low-voltage NFET N<sub>LV</sub> is on. Accordingly, the use of the high-voltage NFET N<sub>HV</sub> in parallel with the low-voltage NFET N<sub>LV</sub> results in a stepped-stage slew rate of the edge transition, where the slew rate of each transition stage is controlled by the sizing of the low- and high-voltage NFETs N<sub>LV</sub> and N<sub>HV</sub> (together with the sizing of the low- and high-voltage PFETs P<sub>LV</sub> and P<sub>HV</sub>).

When the data signal DATA transitions to a low voltage level, inverters 110 and 120 will both output a high voltage level. Accordingly, a high voltage level is applied by inverter 110 to the gates of PFETs P<sub>LV</sub> and P<sub>HV</sub>, turning them both off, in a staged manner, to isolate the high-voltage level VDD from the pad node 150. Again, because low-voltage PFET P<sub>LV</sub> is characterized by a lower threshold voltage than high-voltage PFET P<sub>HV</sub>, PFET P<sub>HV</sub> will turn off sooner than PFET P<sub>LV</sub>, resulting in a stepped-stage slew rate of the edge transition as shown in FIGS. 3A and 3B.

Simultaneously, the high voltage level output by inverter 120 is applied to the gates 122 and 142 of NFETs N<sub>LV</sub> and N<sub>HV</sub>. The application of the high voltage level to the gates 122 and 142 of NFETs N<sub>LV</sub> and N<sub>HV</sub> turns on NFETs N<sub>LV</sub> and N<sub>HV</sub> to pull the pad node 150 to ground in a stepped-stage manner due to the difference in threshold voltages of low-voltage NFET P<sub>LV</sub> and high-voltage NFET P<sub>HV</sub>. In particular, the voltage level on the output pad 150 transitions to ground more quickly when both the high- and low-voltage NFETs N<sub>HV</sub> and N<sub>LV</sub> are on and more slowly when only the low-voltage NFET N<sub>LV</sub> is on.

FIG. 3B shows the output signal PAD seen on pad node 150 with and without the invention. As shown, in the prior art, without the additional high-voltage transistors  $P_{HV}$  and  $N_{HV}$  of the invention, the output signal edge transitioned fully once the threshold voltage of the respective transistors was reached (as limited by the size (i.e., resistance) of the transistor). By staging the transition using transistors with different threshold voltages, the edge transition can be slowed down by essentially delaying the full transition.

It will be appreciated that the number of transistors with differing threshold voltages and connected as shown at 130 and 140 in FIG. 2 can be increased to add further stepped stages, and therefore additional control, of the edge transitions of the signal.

FIG. 4 is an alternative embodiment of a slew rate controlled output driver circuit 200 in accordance with the invention. In this embodiment, output driver 200 includes an inverter 210 which receives data signal DATA. The output of the inverter is connected to the gate of a low-voltage NFET  $N2_{LV}$  and to the gate of a high-voltage NFET  $N2_{HV}$ . The sources of NFETs  $N2_{LV}$  and  $N2_{HV}$  are each connected to the circuit ground, and their drains are each connected to the pad node 250. A pullup resistor 220 is connected between the pad node 250 and a high-voltage source  $V_{DD}$ .

In operation, when the input signal DATA is low, the pad is to be driven low, and the signal is high, the pad is to be driven high. When the input signal DATA undergoes a high-to-low transition, the output of the inverter 210 transitions from low-to-high, and accordingly, a low-to-high transition is applied to the gates of low- and high-voltage NFETs  $N2_{LV}$  and  $N2_{HV}$ , whereby both of them eventually fully conduct and pull the output pad 230 to ground. When the input signal DATA undergoes a low-to-high transition, the output of the inverter 210 transitions from high-to-low, which is applied to the gates of low- and high-voltage NFETs  $N2_{LV}$  and  $N2_{HV}$ , whereby both of them eventually are turned off to isolate the output pad 230 from ground, allowing pull-up resistor 220 to pull the output pad 230 to  $V_{DD}$ . The use of parallel low- and high-voltage transistors results in a staged level of conductance similar to the timing diagram of FIG. 3A and 3B.

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